



# **Motivations**

Finding an analytic proof of **Smale conjecture**: the topological space consisted of unknotted loops is homotopic to the topological space of round circles.

However,

- A topological proof of Smale conjecture was given by Hatcher in 1983 [3].
- It's more natural and intuitive to have an analytic proof of Smale conjecture instead of an abstract topological proof (see [2]).
- \* This poster is based on the joint work in [6].

# Introduction

Assume  $f : \mathbb{R}/\mathbb{Z} \to \mathbb{R}^3$  is sufficiently smooth. Let  $\gamma = |\partial_x f|$ ,  $ds = \gamma dx$  the arclength element, and  $\partial_s = \gamma^{-1} \partial_x$  the arclength differentiation. Denote by  $T = \partial_s f$  the unit tangent vector, by *I* the set of arclength parameter of *f*, and by  $\kappa = \partial_s^2 f$  the curvature vector of f. Define the **bending energy** of f,  $\mathcal{K}[f]$ , by

$$\int_{I} |\kappa|^2 \, ds, \tag{1}$$

and the so-called **Möbius energy** (which is a kind of **electrostatic energy**) of f,  $\mathcal{E}_M[f]$ , by

$$\iint_{S^1\times S^1} \left[ \frac{1}{|f(\sigma) - f(s)|^2} - \frac{1}{D(f(\sigma), f(s))^2} \right] ds d\sigma,$$

where  $D(f(\sigma), f(s))$  denotes the minimum length of subarcs of *f* with end points  $f(\sigma)$ and f(s),  $\sigma$  and s both denote the arclength parameter of *f*. Let the total energy of *f* be

$$\mathcal{E}_{\alpha,\beta,\lambda}\left[f\right] := \alpha \cdot \mathcal{K}\left[f\right] + \gamma \cdot \mathcal{E}_{M}\left[f\right] + \lambda \cdot \mathcal{L}\left[f\right], \quad (3)$$

where  $\mathcal{L}[f]$  is the total length of curve f and  $\alpha, \gamma, \lambda$  are non-negative constants. Note that the Möbius energy  $\mathcal{E}_M$  is induced from a renormalized electrostatic energy. Also, as  $\alpha > 0, \gamma = 0$  in Eq.(3), the total energy functional  $\mathcal{E}_{\alpha,\beta,\lambda}$  corresponds to the Euler-Bernoulli model of elastic curves.

$$\partial_t f = -2\alpha \cdot \nabla_s^2 \kappa - \frac{|\kappa|^2}{2} \kappa + \lambda \cdot \kappa - \gamma \cdot \mathcal{H}_f, \quad (4)$$

Theorem below).

#### Main Theorem

Then,

- smooth for all t > 0;
- satisfies

# **Dynamics of Elastic Knots**

Chun-Chi Lin

National Taiwan Normal University

Below we investigate the  $L^2$  gradient flows of  $\mathcal{E}_{\alpha,\gamma,\lambda}[f]$ . The energy decreasing evolution equation induced from  $\mathcal{E}_{\alpha,\beta,\lambda}$  can be written as,

where the covariant derivative  $\nabla_s \eta$  denotes the normal component of  $\partial_s \eta$ , and  $\mathcal{H}_f : \mathbb{R}/\mathbb{Z} \to \mathbb{R}^3$  is induced from the so-called Gateaux differential of  $\mathcal{E}_M$ . Notice that the leading term of this parabolic equation (4),  $\nabla_s^2 \kappa$ , is fourth-order,  $\mathcal{H}_f$  is a pseudo differential operator of third-order (see [4]), and keeps the curve  $f_t$  away from self-intersection (embedding) all the time. The short time existence of (4) is a standard matter. Notice that  $\mathcal{H}_f$  is non-local, and whose differential-order is less than the highest term

 $\nabla_s^2 \kappa$  in the linearized equation of Eq.(4). Hence  $\mathcal{H}_f$  remains a compact operator between the relevant parabolic Hölder spaces. Therefore, the short time existence can be argued the same as the case of curve-straightening flow (e.g., see [7], in which  $\mathcal{H}_f$  doesn't appear). Thus we just need to focus on the long time existence and the asymptotics (see the Main

Let  $f_0$  be a given smooth initial loop in the Euclidean 3-space. Assume  $f_t$  is the solution of

 $\partial_t f = -\nabla \mathcal{E}_{\alpha,\gamma,\lambda}[f],$ 

where  $\alpha, \gamma, \lambda$  are non-negative constants.

1. the solution of evolution equation  $f_t$  remains

2. the asymptotic solution,  $f_{\infty}$ , is an equilibrium configuration of  $\mathcal{E}_{\alpha,\gamma,\lambda}$ , i.e.,  $f_{\infty}$ 

 $\delta \mathcal{E}_{\alpha,\gamma,\lambda}[f_{\infty}] = 0.$ 

### In the **proof of the main theorem**, the mathematical analysis follows [7], namely it is based on $L^2$ curvature estimates and Gagliardo-Nirenberg interpolation inequalities.

# Numerical Simulations

The algorithm here is an extension of that in [7], where we exploited the divergence form of the main part in the evolution equation and the partition into a second-order parabolic-elliptic system for the position vector *f* and the curvature vector  $\kappa$ . We choose  $\alpha = \frac{1}{2}$ , and write

$$\partial_t f + \partial_s \left( \partial_s \kappa + \frac{3}{2} |\kappa|^2 T \right) + \gamma \mathcal{H}_f = \lambda \kappa, \quad (5)$$
  
 $\partial_s^2 f = \kappa \quad (6)$ 

and discretize the problem using an semi-implicit scheme in time and piecewise-affine finite elements for the space dependence.

#### **Computational Experiments**

Below we show examples in exhibit interesting dynamical behavior for the gradient flow equation in Eqs.(5) and (6).

A (1,12)-knot initial curve Below shows an example of competition between the elastic energy and the Möbius energy during untangling a unknotted loop of (1,12)-knot type into a round circle. Notice that the shape changes rapidly during t = 0.011 and t = 0.013. Here we choose  $\frac{1}{2} = \alpha = \gamma = \lambda$ .



Below is a figure of *elastic energy* via *t*. It shows that the elastic energy was forced to increase before t = 0.01 and then decreased rapidly after t = 0.01. The decreasing of the Möbius energy is responsible for the phenomenon.









# **A Remained Problem**

• Are round circles the only equilibrium configurations of the elastic knot energy,  $\mathcal{E}_{\alpha,\gamma,\lambda}$ , in the class of unknotted loops?

Notice that one already know that round circles are equilibrium configurations of  $\mathcal{E}_{\alpha,\gamma,\lambda}$ for all non-negative constants  $\alpha, \gamma, \lambda$ . Thus if the answer is positive, then combining with our result in [6] gives an analytic proof of Smale conjecture.

# **Other Applications**

There are two aspects in applications. We hope to explore them in the future.

- 1. Constructing approximate solutions of the **N-body problem** (see [1]).
- 2. Modeling over-damped dynamics of
- elastic rods (e.g., bio-polymers, see [7] and [5]).

# References

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