

## Numerical Analysis

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## 1 Norms

### 1.1 Vector Norm Definition and Properties

**Definition 1.1** A vector norm is a function  $\|\cdot\| : \mathbb{R}^n \rightarrow \mathbb{R}$  satisfying the following conditions for all  $x, y \in \mathbb{R}^n$  and  $\alpha \in \mathbb{R}$ .

1.  $\|x\| \geq 0$  ( $\|x\| = 0 \Leftrightarrow x = 0$ );
2.  $\|x + y\| \leq \|x\| + \|y\|$ ;
3.  $\|\alpha x\| = |\alpha| \|x\|$ .

Some of the most frequently used vector norms for  $x \in \mathbb{R}^n$ :



☞ 1-norm:

$$\|x\|_1 = \sum_{i=1}^n |x_i| = |x_1| + |x_2| + \cdots + |x_n|.$$

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**Property 1.1** For any  $x, y \in \mathbb{R}^n$ , the following two inequalities hold.

- Hölder inequality:

$$|x^T y| \leq \|x\|_p \|y\|_q, \quad \text{where } \frac{1}{p} + \frac{1}{q} = 1.$$

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**Definition 1.3** Two vector norms  $\|\cdot\|_\alpha$  and  $\|\cdot\|_\beta$  are equivalent if there exist constants  $c_1, c_2 \in \mathbb{R}$  such that

$$c_1 \|x\|_\alpha \leq \|x\|_\beta \leq c_2 \|x\|_\alpha$$

for any  $x \in \mathbb{R}^n$ .



**Property 1.2** For all  $x \in \mathbb{R}^n$ ,

$$\|x\|_2 \leq \|x\|_1 \leq \sqrt{n}\|x\|_2. \quad (1)$$

$$\|x\|_\infty \leq \|x\|_2 \leq \sqrt{n}\|x\|_\infty. \quad (2)$$

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**Definition 1.4 (absolute error and relative error)** Suppose  $x \in \mathbb{R}^n$  is the exact solution of some problem and  $\tilde{x}$  is an approximation to  $x$ . We define

$$\text{absolute error} = \|x - \tilde{x}\| \quad (4)$$

and

$$\text{relative error} = \frac{\|x - \tilde{x}\|}{\|x\|}, \quad \text{if } x \neq 0. \quad (5)$$

## 1.2 Matrix Norm Definition and Properties

**Definition 1.5** A matrix norm is a function  $\| \cdot \| : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}$  satisfying the following conditions for all  $A, B \in \mathbb{R}^{m \times n}$  and  $\alpha \in \mathbb{R}$ .

1.  $\|A\| \geq 0$  ( $\|A\| = 0 \Leftrightarrow A = 0$ );
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☞ **Frobenius norm:**

$$\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2}.$$





☞ 2-norm:

$$\|A\|_2 = \max_{\substack{x \in \mathbb{R}^n \\ x \neq 0}} \frac{\|Ax\|_2}{\|x\|_2} = \max_{\|x\|_2=1} \|Ax\|_2.$$

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$$\|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^m |a_{ij}|.$$

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$$\|A\|_p = \max_{\substack{x \in \mathbb{R}^n \\ x \neq 0}} \frac{\|Ax\|_p}{\|x\|_p} = \max_{\|x\|_p=1} \|Ax\|_p.$$

**Theorem 1.1** Suppose  $A \in \mathbb{R}^{m \times n}$ . Then there exists  $z \in \mathbb{R}^n$ ,  $\|z\|_2 = 1$ , such that  $A^T A z = \mu^2 z$ , where  $\mu = \|A\|_2$ .

*Proof:* Let  $z \in \mathbb{R}^n$ ,  $\|z\|_2 = 1$ , be a unit vector that satisfies

$\|A\|_2 = \|Az\|_2 = \max_{\|x\|_2=1} \|Ax\|_2$ . Define

$$g(x) = \frac{1}{2} \frac{x^T A^T A x}{x^T x} = \frac{1}{2} \frac{\|Ax\|_2^2}{\|x\|_2^2} = \frac{1}{2} \left( \frac{\|Ax\|_2}{\|x\|_2} \right)^2,$$

for  $x \in \mathbb{R}^n$ . Then  $z$  is a maximizer of  $g(x)$  which implies  $\nabla g(z) = 0$ . Since

$$\nabla g(x) = \frac{(x^T x)(A^T A x) - (x^T A^T A x)(x)}{(x^T x)^2}.$$

Hence

$$\begin{aligned} \nabla g(z) = 0 &\Rightarrow (z^T z)(A^T A z) - (z^T A^T A z)z = 0 \\ &\Rightarrow \|z\|_2^2(A^T A z) - \|Az\|_2^2 z = 0 \\ &\Rightarrow A^T A z = \|A\|_2^2 z = \mu^2 z. \end{aligned}$$





**Remarks 1.1**  $\|A\|_2$  is the square root of the largest eigenvalue of  $A^T A$ . When  $A$  is symmetric,  $\|A\|_2$  is the absolute value of the largest eigenvalue in magnitude.



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**Property 1.3**

$$\|A\|_2 \leq \|A\|_F \leq \sqrt{n} \|A\|_2. \quad (6)$$

$$\frac{1}{\sqrt{n}} \|A\|_\infty \leq \|A\|_2 \leq \sqrt{m} \|A\|_\infty. \quad (7)$$

$$\frac{1}{\sqrt{m}} \|A\|_1 \leq \|A\|_2 \leq \sqrt{n} \|A\|_1. \quad (8)$$

$$\max_{i,j} |a_{ij}| \leq \|A\|_2 \leq \sqrt{mn} \max_{i,j} |a_{ij}|. \quad (9)$$

☞ SVD: The [Singular Value Decomposition](#)

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**Theorem 1.2 (Existence of SVD)** *If  $A \in \mathbb{R}^{m \times n}$ , then there exists orthogonal matrices  $U = [u_1, u_2, \dots, u_m] \in \mathbb{R}^{m \times m}$  and  $V = [v_1, v_2, \dots, v_n] \in \mathbb{R}^{n \times n}$  such that*

$$A = U\Sigma V^T, \quad (10)$$

where

$$\Sigma = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_p), \quad p = \min(m, n),$$

with

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p \geq 0.$$

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☞ The  $\sigma_i$  are called the **singular values** of  $A$  and the vectors  $u_i$  and  $v_i$  the  $i$ -th **left singular vector** and the  $i$ -th **right singular vector**, respectively.

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☞ We usually use  $\sigma_{max}(A)$  to denote the largest singular value of  $A$  and  $\sigma_{min}(A)$  the smallest singular value of  $A$ .