

Why we need high performance linear solver



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Matrix Computation 2016

Maxwell's Equations for electromagnetic waves



$$\nabla \times E = i\omega B, \quad \nabla \times H = -i\omega D$$

$$\nabla \cdot (\epsilon E) = 0, \quad \nabla \cdot (\mu H) = 0$$

Dielectric materials



$$D = \epsilon E, \quad B = \mu H$$

Metamaterials



$$D = \epsilon E + \xi H, \\ B = \mu H + \zeta E$$

Dielectric materials (3D)



Math. model



Eigenproblem



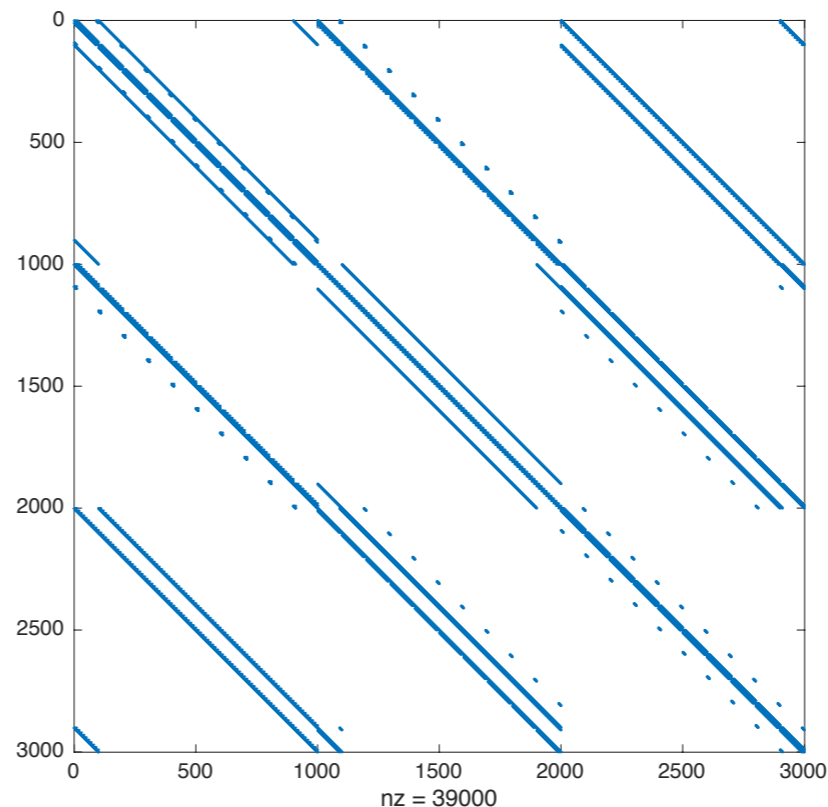
Linear system

sparsity C^*C

$$\nabla \times \nabla \times E(\mathbf{r}) = \omega^2 \varepsilon(\mathbf{r})E(\mathbf{r})$$

$$C^*Cx = \lambda Bx, \quad \lambda = \omega^2$$

$$(C^*C - \sigma B)y = b$$



Complex Media (3D)



Math. model



Eigenproblem



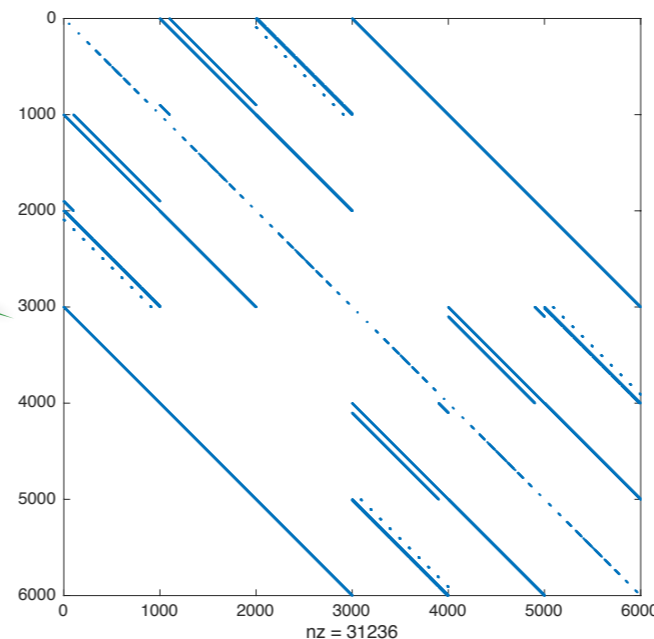
Linear system

$$\begin{aligned}\nabla \times E &= i\omega(\mu H + \zeta E), \\ \nabla \times H &= -i\omega(\varepsilon E + \xi H).\end{aligned}$$

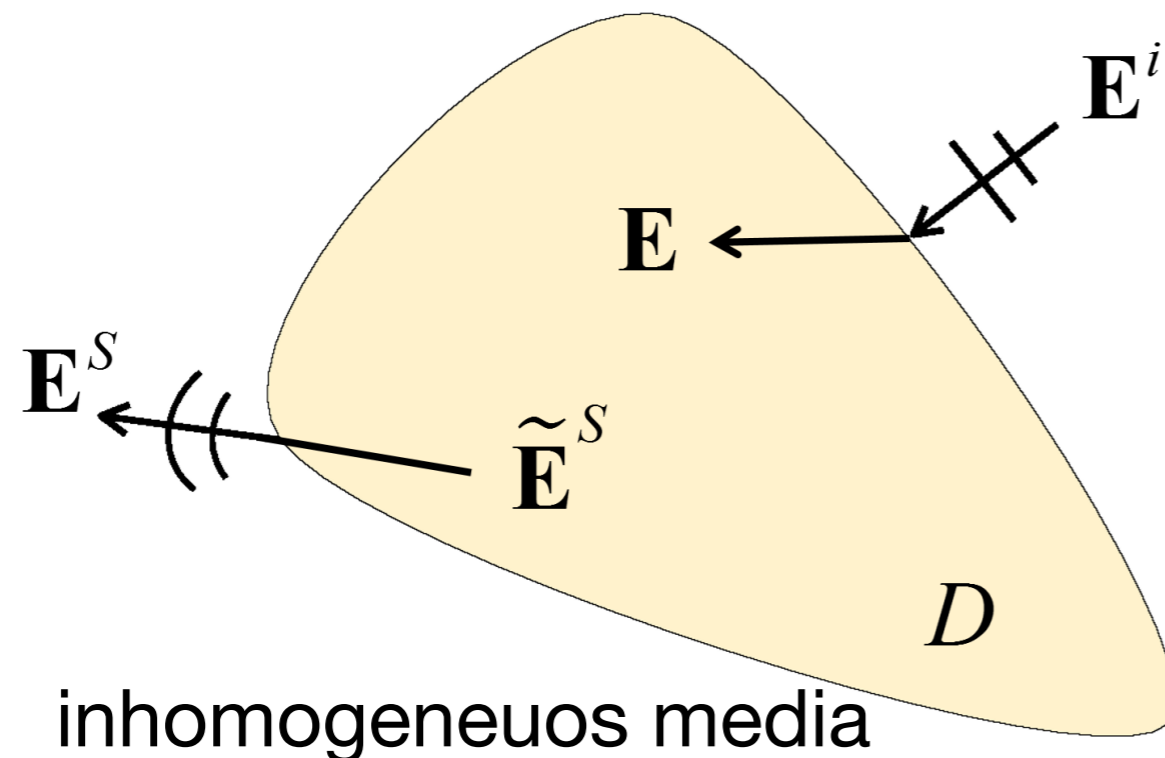
$$\begin{bmatrix} C & 0 \\ 0 & C^* \end{bmatrix} \begin{bmatrix} E \\ H \end{bmatrix} = \omega \left(i \begin{bmatrix} \zeta_d & \mu_d \\ -\varepsilon_d & -\xi_d \end{bmatrix} \right) \begin{bmatrix} E \\ H \end{bmatrix}.$$

$$\left(\begin{bmatrix} C & 0 \\ 0 & C^* \end{bmatrix} - \sigma \begin{bmatrix} \zeta_d & \mu_d \\ -\varepsilon_d & -\xi_d \end{bmatrix} \right) x = b$$

sparsity



Transmission eigenvalue problem for Maxwell's eq.



\mathbf{E}^i : incident wave

\mathbf{E} : transmitted wave

\mathbf{E}^s : scattering wave

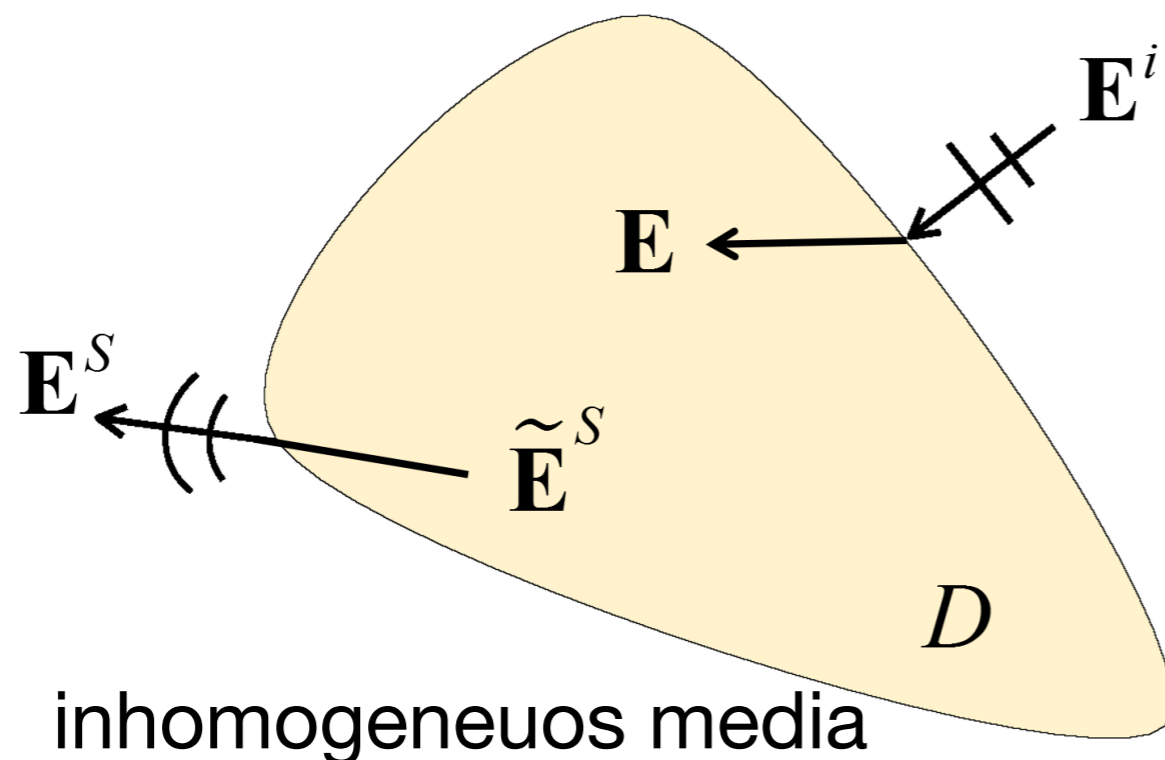
$\tilde{\mathbf{E}}^s$: analytic extension of \mathbf{E}^s

$\mathbf{E}_0 := \tilde{\mathbf{E}}^s + \mathbf{E}^i$

Transmission eigenvalue problem for Maxwell's eq.



$$\nabla \times \nabla \times \mathbf{E} - \lambda N \mathbf{E} = 0 \quad \text{in } D, \quad N = N(\mathbf{x}): \text{ index of refraction}$$



$N, (N - I)^{-1}$ (or $(I - N)^{-1}$): positive definite

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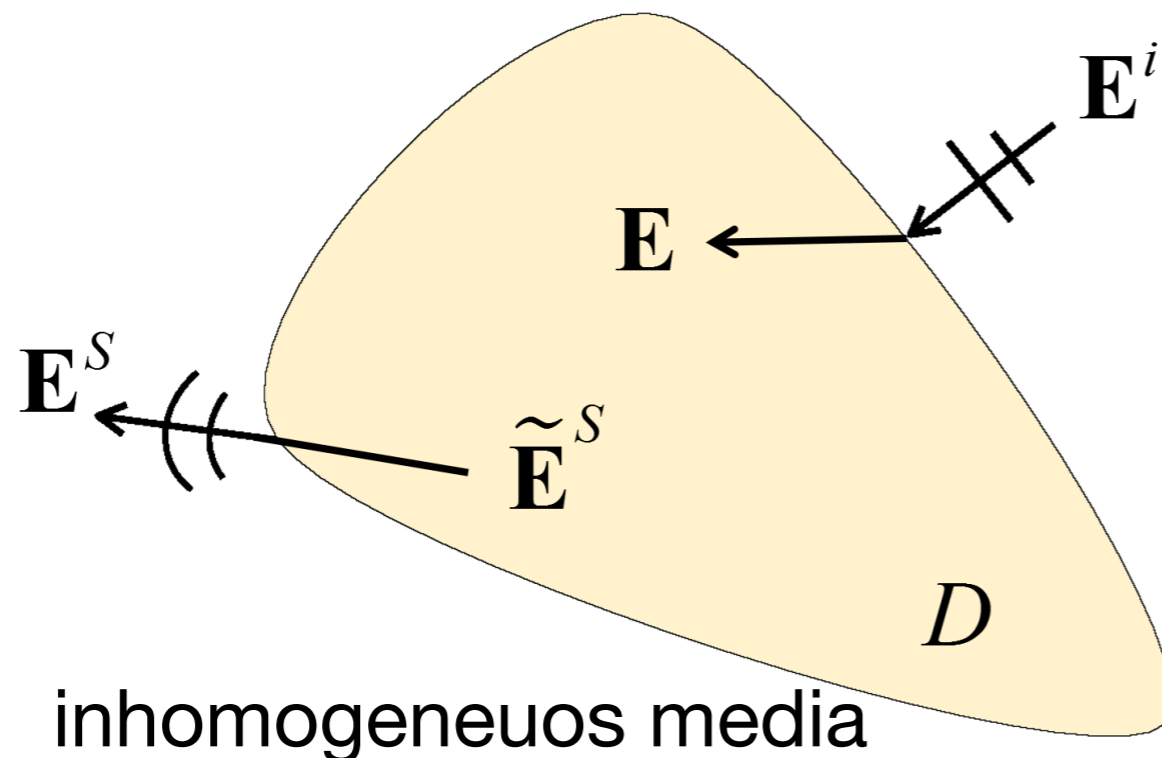
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Transmission eigenvalue problem for Maxwell's eq.



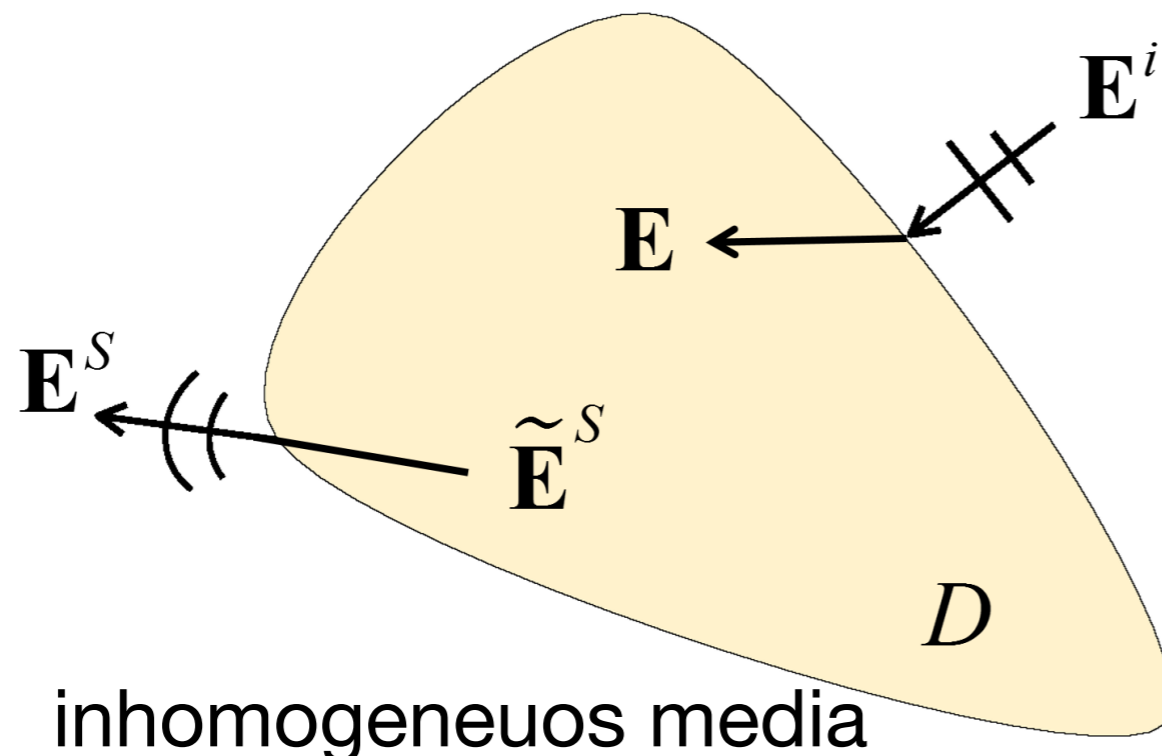
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$$\nabla \times \nabla \times \mathbf{E}_0 - \lambda \mathbf{E}_0 = 0 \quad \text{in } D,$$

$$\mathbf{E} \times \boldsymbol{\nu} = \mathbf{E}_0 \times \boldsymbol{\nu} \quad \text{on } \partial D, \quad \boldsymbol{\nu}: \text{ outer normal}$$

$$(\nabla \times \mathbf{E}) \times \boldsymbol{\nu} = (\nabla \times \mathbf{E}_0) \times \boldsymbol{\nu} \quad \text{on } \partial D$$

$N, (N - I)^{-1}$ (or $(I - N)^{-1}$): positive definite



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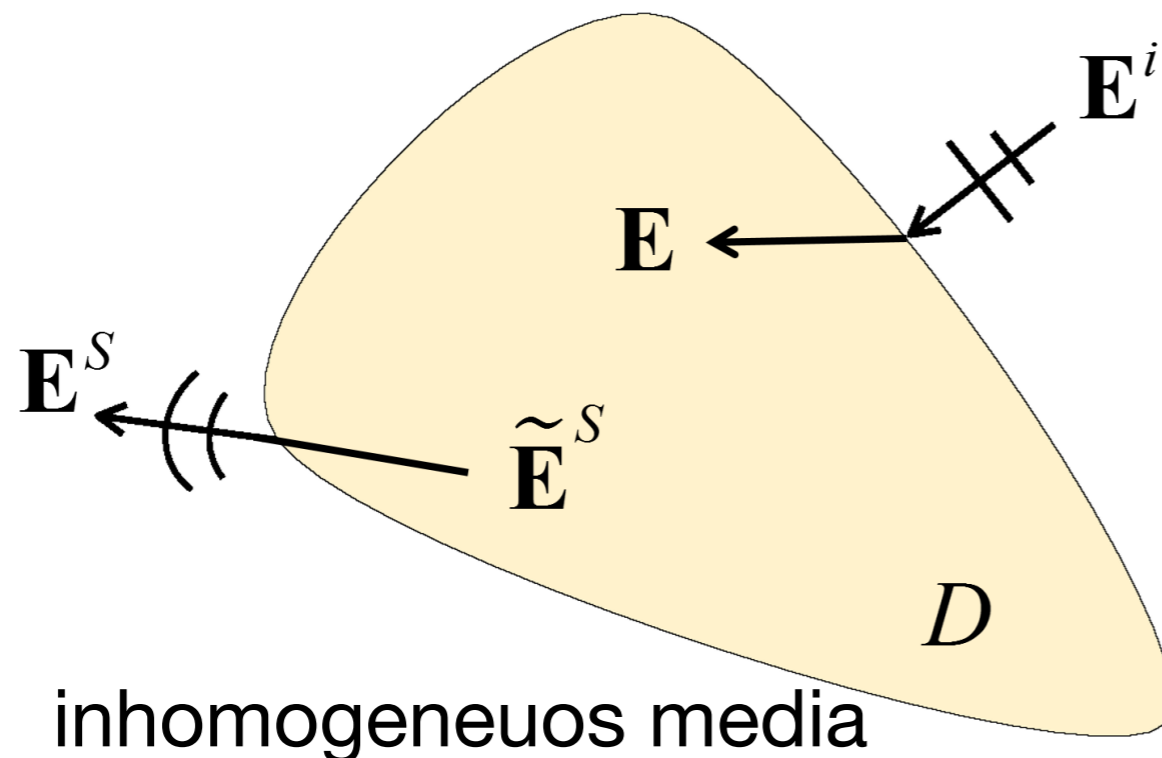
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$$(\nabla \times \mathbf{E}) \times \nu = (\nabla \times \mathbf{E}_0) \times \nu \quad \text{on } \partial D$$

Find smallest positive eigenvalues

$N, (N - I)^{-1}$ (or $(I - N)^{-1}$): positive definite



\mathbf{E}^i : incident wave

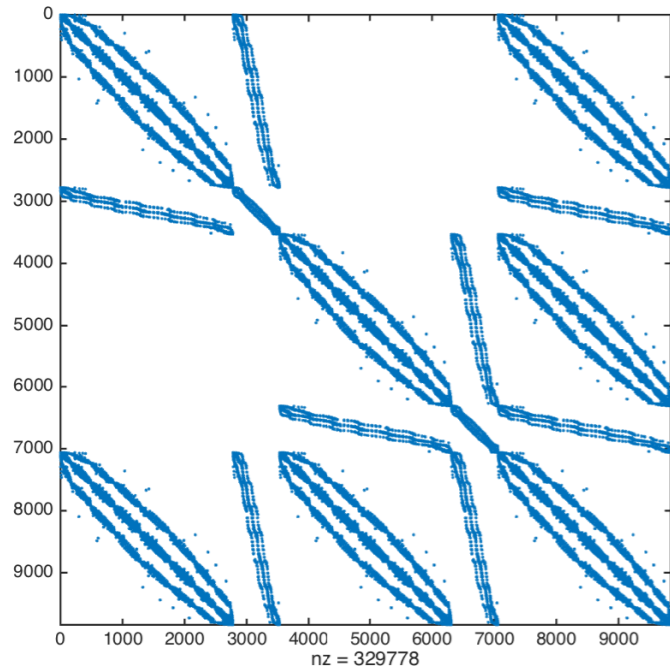
\mathbf{E} : transmitted wave

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$\tilde{\mathbf{E}}^s$: analytic extension of \mathbf{E}^s

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Preconditioning linear system



Solve $(A_0 + \tau(A_1 + \mu_i^{(d)} A_2)) \mathbf{y} = \mathbf{r}_j$



$N(\mathbf{x})$: non-constant

$$\begin{bmatrix} \mathcal{M} & \mathbf{0} & -\mathcal{S}^\top \\ \mathbf{0} & \mathcal{M} & -\mathcal{T}_1^\top \\ \mathcal{S} - \tau\mathcal{T}_1 & \tau(\mu_i^{(d)}\mathcal{T}_1 - \mathcal{S}) & \tau(\mu_i^{(d)}M_1 - K) \end{bmatrix} \begin{bmatrix} \tilde{\mathbf{u}} \\ \tilde{\mathbf{v}} \\ \mathbf{y} \end{bmatrix} = \begin{bmatrix} \mathbf{0} \\ \mathbf{0} \\ \mathbf{r}_j \end{bmatrix}$$